

Routing Guidance for Emerging Transportation Systems with Improved Dynamic Trip Equity

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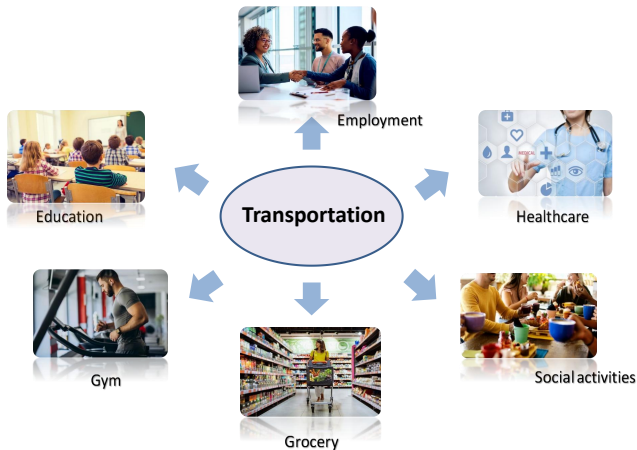


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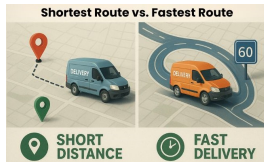
64th IEEE Conference on Decision and Control (CDC), Rio de Janeiro, Brazil
December 10-12, 2025

Transportation Systems





Safety



Efficiency



Sustainability

Negative consequences without “Equity”:

- Reinforces cycles of poverty and social exclusion
- Drive over-reliance on private vehicles
- Exacerbate traffic congestion
- Increase travel costs
- Cause environmental degradation, etc

Static Routing Guidance System (S-RGS)

- Flow-level macroscopic approaches
- Uniform guidance to all vehicles in the same flow
- May shift congestion from one point to another

Dynamic Routing Guidance System (D-RGS)

- Vehicle-level microscopic approaches
- Provide route to each specific vehicle based on real-time traffic data
- Address congestion effectively

Static Routing Guidance System (S-RGS)

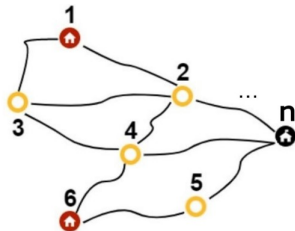
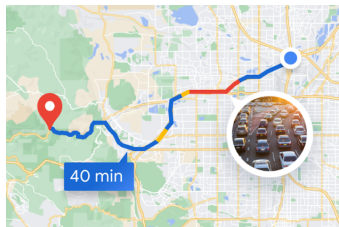
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Dynamic Routing Guidance System (D-RGS)

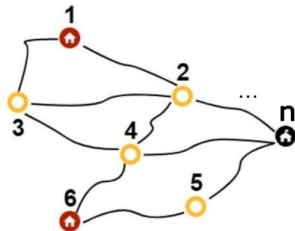
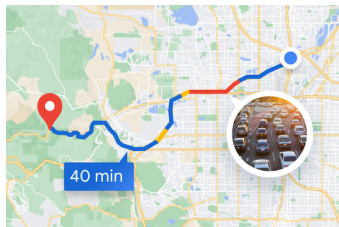
- Vehicle-level microscopic approaches
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Our goal: Develop a D-GRS in emerging transportation systems with enhanced trip equity across vehicle types.

- **Routing Problem**
- **Dynamic Trip Index and Trip Equity (DTE)**
- **Routing Guidance with improved DTE**
- **Simulation Studies**
- **Conclusions and Future Work**



- Feasible route: $r_{1,n} = \{(v_1, v_2), \dots, (v_{n-1}, v_n)\}$
- Decision-making point (DMP): $\{v_k\}$, $k=1, \dots, n-1$
- Set of feasible routes: $r_{1,n} \in \mathcal{R}_{1,n}$

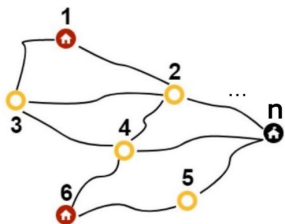


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- Decision-making point (DMP): $\{v_k\}$, $k = 1, \dots, n-1$
- Set of feasible routes: $r_{1,n} \in \mathcal{R}_{1,n}$

Problem: Develop a D-RGS that assists each vehicle in route planning at each DMP.

Key Challenges:

- (i) Take into account real-time and potential traffic congestion.
- (ii) Improve trip equity across travelers despite vehicle types.



► Addressing challenge 1

- Vehicle dynamics between DMPs:

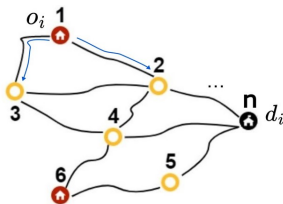
$$a_{k+1}^i = a_k^i + \tau_{k,k+1}^i$$

- Bureau of Public Road (**BPR**) function:

$$\tau_{k,k+1}^i = \tau_{k,k+1}^0 \left(1 + \alpha \left(\frac{f_{k,k+1}^i}{c_{k,k+1}} \right)^\beta \right)$$

where $\tau_{k,k+1}^0$ is the free-flow travel time on (v_k, v_{k+1}) .

► Addressing challenge 1



Flow on **adjacent** edges

- Define monitoring window:

$$\mathcal{M}(a_k^i, \Delta t) := [a_k^i - \Delta t, a_k^i + \Delta t]$$

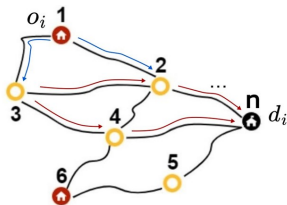
- Define indicator function:

$$1_{a_{k,k+1}^j} := \begin{cases} 1, & \text{if } a_{k,k+1}^j \in \mathcal{W}(a_k^i, \Delta t) \\ 0, & \text{otherwise} \end{cases}$$

- Traffic flow monitored on each **adjacent** edge:

$$\tilde{f}_{k,k+1}^i = \frac{\sum_{j \in \mathcal{N}(t) \setminus \{i\}} 1_{a_{k,k+1}^j} + 1}{2\Delta t}$$

► Addressing challenge 1



Flow on **future** edges

- Given route planning of other vehicles:

$$r_{k',d_j}^*(a_k^i)$$

- Estimate the arrival time of vehicle i :

$$\hat{a}_s^i = \begin{cases} a_k^i + \tilde{\tau}_{k,k+1}^i, & \text{if } s = k + 1, \\ \hat{a}_{s-1}^i + \tilde{\tau}_{s-1,s}^i, & \text{otherwise.} \end{cases}$$

- Traffic flow monitored on each **future** edge:

$$\hat{f}_{s,s+1}^i = \frac{\sum_{(v_s, v_{s+1}) \in r_{k',d_j}^*(a_k^i), j \in \mathcal{N}(t) \setminus \{i\}} \mathbf{1}_{\hat{a}_{s,s+1}^j} + 1}{2\Delta t}$$

► Addressing challenge 2

- Define Dynamic Trip index (DTX)

$$DTX_i(t) = \underbrace{\xi_1 \frac{\tau_{\min}^i}{\tau_i(t)}}_{\text{Efficiency}} + \underbrace{\xi_2 \frac{\phi_{\min}^i}{\phi_i(t)}}_{\text{Cost}} + \underbrace{\xi_3 \frac{q_{\min}^i}{q_i}}_{\text{Convenience}}$$

$$q_{\min}^i = \frac{T_{w,\min}^i}{T_{d,\max}^i}$$

Accessibility
Availability

- Convex combination: $\xi_1 + \xi_2 + \xi_3 = 1$
- τ_{\min}^i : Minimum travel time between (o_i, d_i) .
- $\phi_{\min}^i = \epsilon_{\min}^i \tau_{\min}^i$: Minimum transportation cost.

► Addressing challenge 2

- Define Dynamic Trip Equity (DTE) using **Gini Coefficient**

$$DTE_i(t) := 1 - \frac{\sum_{j \in \mathcal{S}_i(t)} \sum_{j' \in \mathcal{S}_i(t)} |DTX_j(t) - DTX_{j'}(t)|}{2 |\mathcal{S}_i(t)|^2 DTX_{i,\text{mean}}(t)}$$

where

$$DTX_{i,\text{mean}} = \frac{1}{|\mathcal{S}_i(t)|} \sum_{j \in \mathcal{S}_i(t)} DTX_j(t)$$

$$\mathcal{S}_i(t) = (\mathcal{C}_{i,p}(t) \cup \mathcal{C}_{i,a}(t)) \uplus \underbrace{\mathcal{C}_{i,h}(t) \uplus \dots \uplus \mathcal{C}_{i,h}(t)}_m$$

$$\mathcal{C}_i(t) = \left\{ j \in \mathcal{N}(t) \mid r_{k',d_j}^*(t) \cap r_{k,d_i} \neq \emptyset, r_{k,d_i} \in \mathcal{R}_{k,d_i} \right\}$$

Road resource competitors (RRCs)

► Addressing challenge 2

- Perfect DTE in free-flow networks

Since $\tau_i(t) = \tau_{\min}^i$, the DTX is independent of time:

$$DTX_{i,0} = \xi_1 + \xi_2 \frac{\epsilon_{\min}^i}{\epsilon_i} + \xi_3 \frac{q_{\min}^i}{q_i}$$

Proposition 1

Perfect DTE can be achieved in a free-flow network if it satisfies:

$$DTX_{j,0}^p = DTX_{j,0}^a = DTX_{j,0}^h, \quad \forall j \in \mathcal{C}_{i,0}(t),$$

where

$$DTX_{j,0}^p = \xi_1 + \xi_2 \frac{\epsilon_{\min}^j}{\epsilon_j} + \xi_3, \quad j \in \mathcal{C}_{i,0}^p(t)$$

$$DTX_{j,0}^a = \xi_1 + \xi_2 + \xi_3 \frac{q_{\min}^j}{q_j}, \quad j \in \mathcal{C}_{i,0}^a(t)$$

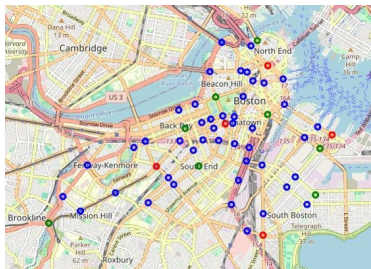
$$DTX_{j,0}^h = \xi_1 + \xi_2 \frac{\epsilon_{\min}^j}{\epsilon_j} + \xi_3 \frac{q_{\min}^j}{q_j}, \quad j \in \mathcal{C}_{i,0}^h(t)$$

Routing optimization problem at each DMP

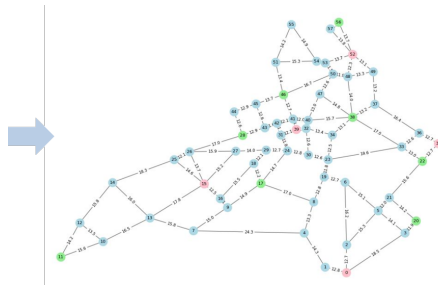
$$\max_{r_{k,d_i} \in \mathcal{R}_{k,d_i}} DTE_i(a_k^i)$$

- Subject to:**
- Dynamic of the vehicle
 - Dynamics of the vehicle's RRCs
 - Monitored traffic flow on adjacent edges
 - Estimated traffic flow on future edges
 - DTX of the vehicle
 - DTXs of the vehicle's RRCs
 - DTE related constraints

An urban road network in Boston



Road network topology



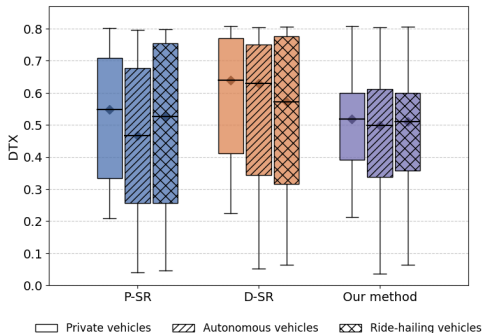
- 58 nodes, including 45 intersections, 8 origins, and 5 destinations.
- Free-flow speed: 27 km/h, nominal travel time is obtained from *OpenStreetMap*.
- Road capacity is set as 5 vehicles per minute per lane.
- Yen's algorithm is used to select the 7 shortest routes from a DMP to each destination when forming the feasible route set.

Parameter settings of each vehicle type

Vehicle type	ξ_1	ξ_2	ξ_3	ϵ_i [\$/\text{min}]	$T_{w,i}$ [min]	$T_{d,i}$ [h]
$i \in \mathcal{N}_p(t)$	0.4	0.4	0.2	0.27	2	24
$i \in \mathcal{N}_a(t)$	0.4	0.4	0.2	0.1485	15	18
$i \in \mathcal{N}_h(t)$	0.4	0.4	0.2	0.1536	6	12

- 1,000 vehicles depart between 08:00–10:00 am.
- **Private vehicles** (500); **autonomous vehicles** (300); **ride-hailing vehicles** (200).
- Each ride-hailing vehicle serves 2 travelers.
- $\Delta t = 60$ seconds.

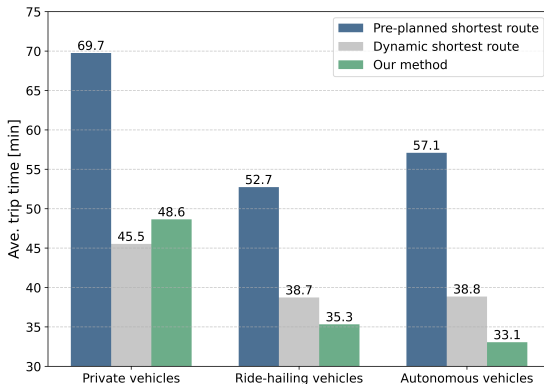
Comparison of the dynamic trip index (DTX)



- Pre-planned shortest-route (P-SR)
- Dynamic shortest-route (D-SR)

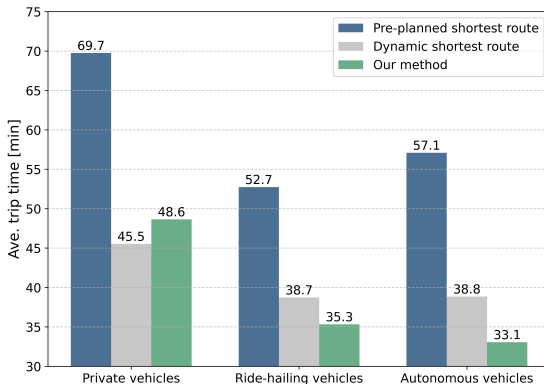
- The DTEs for the completed trips of all vehicles in P-SR, D-SR, and our methods are 0.734, 0.777, and **0.818**, respectively.
- The proposed method achieves a more centralized distribution of DTX across all vehicle types, showing a more consistent and balanced trip equity.

Comparison of the average trip time in different methods



- The proposed method significantly reduces the average trip time for **private**, **ride-hailing**, and **autonomous vehicles** by approximately 30%, 33%, and 42%.

Comparison of the average trip time in different methods



- The proposed method significantly reduces the average trip time for **private**, **ride-hailing**, and **autonomous vehicles** by approximately 30%, 33%, and 42%.
- Our method effectively redistributes travel costs across vehicle types via route optimization, contributing to a more equitable and efficient transport system.

Conclusions:


- We present a novel framework to quantify trip equity in a dynamic emerging transport system, integrating trip time, cost, and convenience.
- We develop a D-RGS to optimize vehicle routes dynamically, which
 - (i) incorporates **real-time** and **anticipated** traffic congestion;
 - (ii) **enhances travelers' trip equity** despite vehicle types.
- We establish conditions ensuring the best trip equity in free-flow networks.

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Future work:

- Accurate traffic congestion estimation on future edges.
- Incentive design to enhance compliance with route recommendations.



Thank you for your attention!

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